

Alert System for Forest Fire Detection Using CNN Algorithm

Mrs.R.Sujatha

Department of Information Technology
M. Kumarasamy College of Engineering
Karur, Tamilnadusujathar.it@mkce.ac.in

K.M.Gokul

Department of Information Technology
M. Kumarasamy College of Engineering
Karur,
Tamilnaduharishgokul096@gmail.com

M.Dinesh

Department of Information Technology
M. Kumarasamy College of Engineering
Karur,
Tamilnadudinesh.m4601@gmail.com

T.Gopinath

Department of Information Technology
M. Kumarasamy College of Engineering
Karur,
Tamilnadugokulkannangopi483@gmail.com

C.Dineshkumar

Department of Information Technology
M. Kumarasamy College of Engineering
Karur,
Tamilnadudkchellamuthu3731@gmail.com

Abstract—Serious hazards to infrastructures, ecological elements, as well as human existence come from forest fires. By 2030, it is anticipated that wildfires would have decimated half of the forest ecosystems. Implementing fire detection techniques is the only viable method for reducing forest fire damage. As a result, colleges and universities all across the world are paying close attention to forest-fire detection systems. Several commercial automatic fire sensor systems are currently available, however they are all difficult to employ in broad open areas like woods due to poor response times, expensive maintenance needs, and other difficulties. Representation handing out has been used in this study due to the quick development of digital camera technology, the camera's excellent ability to cover large areas, the fact that image processing methods respond more quickly than established sensor systems, and the fact that image processing systems are typically less expensive than sensor systems. Because some things share characteristics with fire, making accurate forest fire detection algorithms difficult, false alert rates may be significant. In this project, a novel four-stage method for detecting forest fires using video-based image processing is presented. To find moving regions, a background-subtraction technique is used first. Secondly, RGB colour space is used to identify possible fire zones. Finally, because candidate zones may contain moving fire-like items, features extraction is used to differentiate between actual fire and fire-like items. Ultimately, using the convolutional neural network technique, the region of interest is categorised as either true fire or non-fire. The final experimental findings demonstrate that the suggested approach successfully locates forest fires.

Index Terms—Convolutional neural network, Deep learning and detecting forest fires, processing images, Machine learning

I. INTRODUCTION

The effects of human activities on the woodlands in general are very severe. The spread of forest regions is a result of the population's fast increase and urbanisation. A natural threat to nature and the involvement of the atmospheric system is a forest fire. The environment has an impact on living things. As a tool for conformity with burn zones and damage assessment, satellite imagery also provides a fire monitoring, control, and range of acceptable fires. The term "satellite image" describes the capacity of images from datasets acquired in remote locations to receive certain

information. A satellite sensor captures an image of a forest fire, but the range of temporal resolution and forest area coverage is growing. A tool for managing and locating damaged equipment for conformity with burn zones and understanding a favourable fire spectrum was also made available via satellite photos. Checking the constancy of the colour is the key to categorising this fire and other components from the original fire. This issue has been fixed, and the recommended approach lowers the error. In addition to detecting fires, it can tell the difference between a fire and a material fire. The assumptions established in the proposed system operation to assess the forest fire, include the system's threshold Value, matrix valued detection, and differential matrix valuation.

On Earth, wildfires are a common natural occurrence. Each year, forest as well as animals are lost as a result of wildfires. Significant numbers of lives are lost, as well as valuable natural assets as well as private property. Our climate system is significantly impacted by the forest fire. The issue has gotten worse than in prior years. A significant contributor to forest fires is human encroachment on forested regions. Finding and putting out the fire in its early stages is crucial. Powered tools or people are used in conventional fire defence strategies to keep an eye just on environment. The most popular fire smoky detection methods typically rely on temperatures sampling, element sampling, as well as air photograph testing. If the nanoparticles do not disperse the sensors and activate them, no alarm is raised. Because of the tremendous improvement in image processing technology and the decline in price of digital cameras, fire detection fully based on image analysis is more practicable than some other traditional ways like fire watch towers, sensors, satellite, and many others. People are essential to look about the area at some time inside the case of fires watch towers. The main issue with this method is its lack of precision due to worker weariness, the hour of day, the location, as well as other factors. Sensors are devices that can detect their surroundings and calculate data. In addition to chemical parameters like monoxide, dioxide, and nitrogen dioxide, the sensors also measure biological data like strain, temperature, and humidity.

Covering hugewooded areas with a wireless camera fire detecting device is unfeasible as a result of the prerequisite of an abnormal distribution of sensors nearness. Battery cost is another significant issue. A vast area can be revealed by satellite-based equipment, however the quality of satellite images is poor. Since a hearth can only be spotted after it has expanded quite a bit, real-time detection is not possible. Additionally, the cost of these systems is exorbitant. Clouds, for example, will significantly lower the effectiveness of landsat forest detection of fire.

In contrast to conventional methods, fireplace detection techniques based on visual processing may monitor the forested area in real-time for twenty-four hours. It has the ability to sound alarm even while a fire is still very young. Also, the price of the photoprocessing method is lower since the algorithms' calculation costs are reasonable. In the case of detecting forest fires, it is practicable to identify the fire by recognising the distinction between the colour of the forest (green) and the fire (red), or by using the distinction between subsequent photographs to find the quick generation of smoke. Smoke assessment has the drawback that it cannot offer further information, such as the location of the fireplace, the size of the fire, or the fire's changing charge. Therefore, looking for fire pixel in a photo is more reliable than looking for smoke debris. Fig 1 suggests numerous wooded area fires in diverse situations.

II. RELATED WORKS

Jianmeizhan et al. [1] offered for segmentation and recognition, exercise ATT Squeeze U-Net. The SqueezeNet design was combined with a modified Fire module on the ATT U-Net, allowing for more efficient feature learning even with little data. Then, a separate recognition model that incorporated a portion of the previously identified encoding path was used for the classification process. This investigation confirmed its efficacy on fire identification where high sensitivity was necessary and little machine learning model could be gathered, in addition to offering existing segment as well as recognition frameworks a more effective substitute. Experiments revealed that the suggested architecture produced dependable recognition and segmentation accuracy that was competitive. Although pretty precise combustion conditions were alarms and fire zones possibly will be segregated within minute precision, there may further more limits for the reason of wide-ranging fire detection.

Xuanbing Qiu and co. al [3] Using Using a high-performing microcontroller and the simple DLIA algorithm, a reliable and flexible gas sensor system for early-warning fire detection has been created. The sensor is reliable, accurate, and quick to react, with a LoD of CO of 0.0875% and an integration time of 24S. Expanded polystyrene and A4 paper are among the fire-hazardous materials that had reaction times ranging from 230 to 110 seconds, although PVC, beech wood, and cotton rope have reaction times ranging from 680 to 250 seconds since the detection threshold was set at 5 ppm rather than 100 ppm.

The overall effectiveness of the CO gas sensor system has met the needs for field use. Studies will be expanded to measure CO₂, H₂O, and CH₄ in actual fire smouldering conditions using different laser spectroscopies operating at the proper wavelengths as the detecting light sources. For laser-based sensor systems that will offer high sensitivity, strong selectivity, and quick response, a wide range of applications in the sectors of coal gas detection, environmental detection, and industrial control are anticipated.

Bing Liu, et al [2] realized CNN-accelerator on the Xilinx ZYNQ-7100 device to accelerate standard as well as depth-wise separable convolution. The network layer acceleration of various scales among customizable architecture developed could be understood by the ZYNQ's varied mode that is intensive on single-computing engine mode. In order to maximise bandwidth and decrease wait times caused by on-chip to off-chip data exchange, the Mobile Net coupled with SSD network model implements three stream buffers on-chip that use the data stream interface to position the ping-pong buffer mode. By comparison, the suggested solution yields a fully pipelined state with the smallest latency. The accelerator outperformed earlier designs with a computation capability of 17.11 GFLOPS at a clock frequency of 100 MHz and great resource usage. a CNN accelerator for the Xilinx ZYNQ 7100 platform that accelerates both normal convolution and depth-wise separable convolution. The heterogeneous mode of ZYNQ allows the accelerators constructed only on human engine mode to accomplish physical network acceleration of various scales under the flexible architecture we suggested. Using the Related contract + SSD network setup as an example, the accelerator computed the global ideal computing parallel ratio of the total infrastructure. To enhance bandwidth and reduce the latency caused by on-chip off-chip sending data, the three targets' chip-based buffers employ the streaming data interface and are set to the ponging buffer mode. Regardless of whether it uses layer wise separable convolution or standard compression, the aforementioned method generates a complete pipelined state with significantly less latency than the non-pipelined state.

Oktao Ozan, et al [4] presented modern model employing attention gate employed to segment medicinal image. Our method eliminates the necessity for a third-party object localization model. The suggested method is comprehensive and modular, making it simple to apply to image classification and regression applications like machine translation and natural image analysis. According to experimental results, these suggested AGs are definitely highly useful for tissue/organ detection and localization. This is especially true for small, flexible organs like the pancreas, and comparable behaviour is expected for jobs requiring global categorization. Learning and inter training programmed can help AGs improve their training behaviour. To initialize the attentiveness network, for example, which was before U-Net weights can be employed, and gates can be taught appropriately during the fine-tuning step. Similar to this, a significant body of work studying various gating structures exists in machine learning. For

improved gradient training algorithm and slightly weaker attention mechanisms, highway networks, for instance, use residual connections surrounding the gate block.

Lizhong Hua, et.al[5] Similar technologies for tracking purposes fire tracking systems with forest masks to monitor forest fires. The often used NDVI-based masks, however, might not be able to tell woods from other types of vegetation. More accurate techniques for extracting forests must be developed and included into fire monitoring systems in order to effectively anticipate, identify, and monitor forest fires. Threats from forest wildfires to worker health, wildlife habitat, local economies, as well as global warming are severe and expanding. Forest fire and other stakeholders must keep track of forest fires in a timely and accurate manner. Monitoring the occurrence and progression of forest wildfires using spaceborne technology has evolved into a useful and alluring technique. Here, we provide a summary of the guiding principles and to use cases for monitoring forest fires using satellites as well as unmanned aerial vehicles (uavs infrared sensor networks (IRRS)). Four categories of FFM-relevant IRRS techniques are recovered in this review: the techniques of bi-spectral, specified limit, spatially contextual, as well as number of co

The detection and separation of smoke from a single visual frame were investigated and tested by Hongda Tian et al. [6]. In specifically, an optimization strategy enabling the isolation of semi and semi components was developed utilising dual over-complete dictionaries and was based on the imaging model. The appropriate sparse values for detection are concatenated to create a unique feature. Also, a method based on the hypothesis that picture matting is genuine has been developed to tell the true smoke from the background from results of automated detection. Numerous detection trials were run, and the findings show that the suggested feature works substantially better than the current smoke alarm features. This indicates the efficacy of the detecting product. Furthermore, in a grayscale, the proposed approach may identify smoking from other challenging elements such as fog/haze, mist, shadow, and so on. The suggested separation approach may successfully predict and separate the real smoke and background components, according to experiments on smoke separation. The fog component's complex modelling, such as kernel- or car modelling, may result in further improvements.

A F Saputra, et.al[7] Work should be done to develop an automated system for monitoring the status of a home that is capable of spotting possible disaster early on. Yet, because a fire can start at any time and spread quickly, the mechanism will release the door to give immediate admission and exit access, ensuring a safe escape. The created system is anticipated to execute an essential disaster reaction action in an effort to prevent any falling casualties. This research focuses on fire detection and house monitoring through the use of a wireless sensor network with four sensors, including smoke, carbon monoxide, temperature, and air humidity sensors. If the system determines that there is a high fire chance, it will unlock the door to the house, activate the alarm, and alert

the user. The technology is capable of sending notification to users accurately based on the results of trials and testing. However, a fire probability estimation mistake of down to 0.3% ratio is still possible.

Zhijian Yin et al. [8] offer a smoke detection deep normalisation and neural network convolutional neural network method (DNCNN). Our network employs batch normalisation to expedite training and increase smoke detection precision. DNCNN automatically features extracted for smoke detection, in contrast to techniques that rely on manually created features. According to experimental findings, the DNCNN concurrently achieves excellent detection rates and poor false alarm rates. Additionally, we confirm the value and potency of feature extraction for our DNCNN, particularly in cases where the training dataset are inadequate and unbalanced. The majority of currently used algorithms are built on a framework of manually created features. However, these current algorithms have a very tough time achieving lower false alarm levels without lowering detection rates. The primary cause is the extreme variation in colour, texture, and shape of smoke. Smoke also distorts visual scenes, creating unsteady features. The manual creation of discriminant features for fire detection is a time-consuming and expensive process.

A multivariate dynamic texture analysis descriptor of higher cognitive Linear Dynamical Systems was presented by Kosmas D. Poulo et al. [9] (h-LDS). We demonstrated that we can outperform conventional linear dynamical systems in terms of detection rates by using higher order decomposition to the multidimensional picture data. Additionally, experimental results showed that we might increase the classification accuracy by adding more elements to the multidimensional picture patch. In this study, we used the displayed features space of the HOG descriptor as a new picture element for smoke detection; however, in the future, other descriptors might be used to enhance the data input into h-LDS again for identification of a range of dynamic textures, such as water, fire, steam, etc. A unique methodology was proposed that allows the encoding of video subsequences into scatter plots of h-LDS descriptor generated by the candidate picture patch in each subsequence in order to apply multidimensional static wavelet transforms to a video-based early warning system. The robustness of the methodology was additionally enhanced by combining this study with spatiotemporal modelling utilising a particle swarm optimization method.

Wolfgang Krull, et.al[10] Because huge, highly intense forest fires are largely unpredictable and pose very significant hazards, emphasis must be placed on early smoke detection. A remote UAV can be flown to a region where a fire is suspected to determine if the source of smoke is most certainly a fire, reducing false alerts from conventional clip systems, especially in difficult-to-access terrain. Due to its great resilience to annoyances like steam, fog, particle pollution, and condensing water, the

UAV has semiconductor gas sensors. As a result, it is feasible to distinguish among a large number of false alarms. A blimp can serve as a fireguard after putting out forest or wildland flames. Semiconductor gas sensors and an aspirating fire detection system are employed coupled with the blimp's increased payload. This programme allows for the confirmation of alarms in both indoor and outdoor settings while detecting even the smallest amount of smoke and gas. Because of smoke emissions, dust, or fog, a 2.3GHz measurement device is capable of detecting fire even when there is inadequate visibility. Microwave radiation may permeate things such as leaves and thin walls. The existing configuration may be made much smaller by using chip-based elements.

III. CONVENTIONAL METHODS TO DETECT FOREST FIRE

Due to the tremendous impact that forest fires cause to society and the environment, forest fire identification has been a focus of many experts for the last 10 years owing to an increase in backcountry wildfire case reports from across the world. Human activity and natural factors are two major causes of forest fires. Torching, chewing and tossing cigarettes, electrical wire flashes, fire hazards use while hunting, outing wildfires, shepherd fires, and stubble consumption are all examples of human-caused woods fires. Lightning strikes generate natural forest fires because of the high environmental temperature, and so forth. Climate factors such as temperature and relative dampness, wind direction, rainfall, striking possibility of lighting; period factors such as Christmas season, month, time; population-based factors such as population thickness, human activities in the timberland, human practices; scene factors such as tree types, slant, distance from agricultural land and man-made factors are the primary factors for wood fires. Despite the fact that vision-based sensors offer a number of promising properties, they still have issues with changing lighting conditions, complex environments, and reduced camera picture quality due to network constraints. Researchers have thus tried to triumph over these problems. For instance, explored pixels in dynamic zones and both temporal and spatial wavelet analysis are done. The approach shows potential results, but because it relies on a number of heuristic thresholds, it cannot be used to detect fires in the real world. Examined 3 distinct models for fire zones in images including spectrum, spatial, and temporal models are examined. They make an assumption about the irregularly shaped of fire in their method, however this is not always true because objects can also modify their shape. A novel contour-based fire detection approach for forests based on wavelet analysis and FFT is provided. They then looked into the YCbCr colour model as well as the brightness and luminance components, which resulted to a classification of flame pixels based on rules. The authors looked at a different colour model called YUV and motion to determine if certain pixels were candidates for fire or not. In addition to the research of colour models, a Bayes classifier and certain low-level

attributes of fire zones, such as skewness, colour, roughness, area size, and so on, were used to detect frame-to-frame variations in order to identify fire. Another approach is provided that takes a lookup table into account for the temporal variation-based detection and confirmation of fire zones. The heuristic elements of this strategy reduce the likelihood of reaching the same results when the input data is changed.

IV. PROPOSED METHODOLOGIES

Fires are one of the world's most pressing issues right now, owing to the planet's present state of global warming. We are all aware of what flames are and how they may do significant damage to humans, animals, and other kinds of life. Fire damages vary, and these damages are heavily influenced by the source of the fire, but regardless of how numerous and diverse causes exist, the damage may be catastrophic on a huge scale and impossible to estimate, and in general, fire losses are classified as loss of life and loss of money. In this study, we created an algorithm that integrates fire colour information with fire edge information. The combined findings from both methodologies are then used to generate a parameter that extracts the required data from the photos to detect and identify the fire. Based on the deep learning algorithm, we offer a system that detects the presence of fire automatically. Deep learning is a subset of machine learning that is wholly based on neural networks. Since neural networks replicate the human brain, deep learning is likewise a simulation of the human mind. Pre-processing moves to remove the noise of images has been put into practice; following features extraction step so as to remove the color features and fragment the fire provinces. In the end categorization of pixels by means of deep learning algorithm through competent mobile alert coordination is established

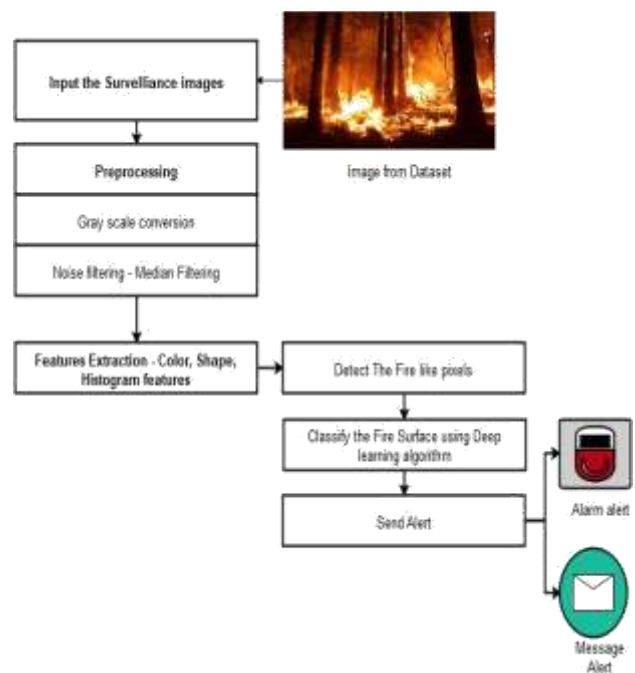


Fig1: Proposed framework

4.1 Image Set Upload

Early identification of wildfires, which is critical to the protection and security of natural areas, is one of the most significant and challenging challenges confronting the government and forest fire management. The main factor reducing the size of the forest is forest fire. This fire detection method also eliminates the need for human processes, aids in monitoring, and helps to safeguard challenging-to-protect locations. Regardless of the weather or time of day, the novel technique is utilised to enable the development of systems that provide for detailed monitoring. We can upload images or movies from CCTV footage taken in the forest in this section. The image of a forest fire is captured using a satellite sensor, but the range of temporal resolution as well as forest area coverage is expanding. Satellite photos were also used to monitor and locate damaged equipment in order to comply with burn zones and comprehend a safe firing variety. The key to distinguishing this fire and other components from the original fire is to check the consistency of the colours. This issue has been fixed, and the recommended approach lowers the error. In addition to detecting fires, it can tell the difference between a fire and a material fire. Threshold value, matrix value detection, and differential matrix value were the features employed in our proposed system operation to analyse the forest fire. Convert input video files into frames if it is video, or the input photos can be in any form or size if it is images.

4.2 Median Filtering

Pre-processing refers to procedures in which the input and output pictures are intensity images, which is the most basic level of abstraction. These well-known images are of the same sort as the original sensor data, with an intensity picture commonly represented by a matrix of picture function values (brightnesses). There are four types of picture pre-processing algorithms based on the size of a pixel neighbourhood used to determine the new pixel brightness. Although spatial image transformations (such as rotation, scaling, and translation) are classified as pre-processing methods because similar techniques are used, the goal of pre is data enhancement that suppresses reluctant distortions or enhances a few image features critical for further processing. To begin further processing, the user must choose the necessary lung frame image. Each image is then scaled down to 256×256 . After that, apply a median filter to clean out the noise in lung images. The median filter is a linear digital filtering algorithm that is widely used to remove noise from an image or signal. This type of noise reduction is a popular pre-processing approach used to improve the results of post-processing (for example, edge detection on an image). Due to its uses in both signal processing and digital image processing, median filtering is frequently employed to maintain edges while reducing noise (though see discussion below). The median filter's primary principle is to iteratively replace each element in the signal with median of its nearby entries. A nonlinear technique for removing noise from photographs is median filtering. Since it effectively reduces noise while keeping edges, it is commonly employed. It works especially well to eliminate "salt and

pepper" noise. The median filter operates by going pixel-by-pixel through the image and substituting each value with median of its neighbours. The neighbourhood pattern is known as the "window," and it goes over the entire image pixel by pixel. After numerically ranking all of the picture pixels from the window, the median is calculated by putting the pixel under consideration in lieu of the centre (median) pixel value. Convert an RGB image to grayscale in this module, and use the median filtering process to eliminate image noise.

4.3 Color Features Extraction

The purpose of feature extraction is to minimise the resources required to correctly describe a large amount of data. One of the most difficult aspects of interpreting complicated data is the sheer amount of variables involved. For an analysis with a large number of variables, a classification approach that overfits a training sample and performs poorly on fresh sample generalisation is usually required. Feature extraction is a method of producing variable combinations to overcome these difficulties while still correctly characterising the data. A surface's tactile or visual characteristics are its texture. In order for them to be utilised for reliable, precise segmentation and classification of objects, texture analysis seeks to identify a unique way to express the underlying features of textures. It does this by describing these characteristics in some simple but unique form. Only a small number of designs support onboard textural feature extraction, despite the fact that texture is crucial for image analysis and pattern identification. Texture and color features are implemented in this module. Utilizing the Grabcut approach, HSV colour features are retrieved, and texture data include statistical features. The snake model is used in this module to split skin pictures. A snake is a deformable, energy-minimizing spline that is drawn towards object outlines by restriction and image forces, as well as internal forces that inhibit deformation. Snakes can be seen as a specific case of a general method of energy-minimization-based deformable model-to-image matching. Extract the features relating to colour or form from this module. We could extract the fire zones from photos based on these attributes.

4.4 Fire Recognition

The system's classification comes as its last phase. After understanding the structure, the likelihood of true positives was separately assessed for each segment. Utilizing a convolutional neural network method, brain disorders are categorised. CNNs are feed-forward neural networks that include various combinations of convolution layer, max pooling layers, and totally related layers. CNNs can take advantage of spatially localised correlation by requiring a tight connection pattern between neurons in neighbouring layers. Max pooling layers and convolutional layers alternate, simulating the individuality of complicated and clear cells in mammalian visual cortex. A CNN starts with one or more pairs of convolutional and maximum pooling layers and finishes with neural network that are entirely connected. It is consistently demonstrated that the hierarchy

of CNNs is the most effective and successful way to assess visual representations. We are aware that CNNs can perform as well as or even better than humans in various visual tasks, and this knowledge motivates us to investigate the feasibility of using CNNs to classify disease traits. The convolution and max pooling layers, as well as the networks' training methods, vary between CNNs. Finally, use a deep learning algorithm to classify the image regions, and then increase classification accuracy

4.5 Alert System

Human activity has a significant negative impact on the woods as a whole. The spread of forest regions is a result of the population's fast increase and urbanisation. A natural threat to nature and also the involvement of the atmospheric system is a forest fire. The environment affects living things. Satellite imagery also provides a tool for fire monitoring, management, and damage assessment in order to comply with burn zones and grasp a favourable fire range. The term "satellite image" describes the capacity of images from datasets acquired in remote locations to receive certain information. Send an Alert message to the authorities in this module when a fire is detected. The ability to just provide earlier detection may be helpful.

4.6 Experimental Results

In this study, a framework for detecting has been implemented through Python based on real-time datasets was gathered from KAGGLE web sources.

For analysing the system's performance the following metrics such as correctness, sensitivity, specificity, error rate, and precision are taken into account.

Number of genuine positives - the best possible positive forecast

False positives (FP) are the number of inaccurately predicted positive outcomes.

Number of genuine negatives - perfect forecast of a negative outcome.

Negative result (FN): number of accurate negative predictions minus the number of actual negatives

The percentage of overall flawless forecasts to the complete test data is known as accuracy (ACC). Additionally, it can be written as $1 - ERR$. The maximum accuracy is 1.0, and the minimum accuracy is 0.0.

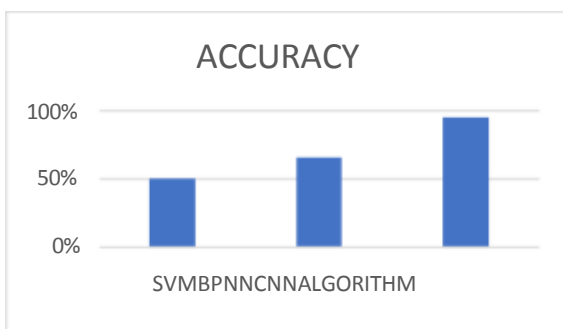


Fig2: Performance chart

The graph above shows that the CNN algorithm has a higher rate of accuracy than the current algorithms.

V. CONCLUSION

The method for recognising images of forest fires using CNN is provided in this research. Its primary characteristic is the use of the flame picture in training and assessment. After that, the CNN model is presented, and a solution to the issue that the conventional pool method in Back propagating neural net (BPNN) may occasionally weaken the picture features is suggested. Based on tests, the impacts of learning algorithm, packet size, and certain other parameters on CNN performance are examined, and the ideal values are established. The image feature of the non-flame region within hidden layer is decreased and the characteristic, such as texture and shape is enhanced as a result of the extraction of the candidate flame area based on colour feature. Adaptive pooling is used to prevent picture information loss, and it increases the rate of fire recognition in fire areas compared to original images without segmentation. It has been demonstrated that the suggested method is workable and has a high recognition rate.

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